Simple, Compact Inverters

JX Series

Easy-to-use Inverters for simple applications

- Compact models with a wide range of capacity from 0.2 kW to 7.5 kW.
- Main circuit adopts upper/lower wiring as with contactor.
- Side-by-side mounting contributes to space saving. *
- PID Control
- Built-in radio noise filter for three phase type.
- Built-in RS-485 Modbus
- * Some models have restrictions in the ambient temperature, carrier frequency, and output



Performance Specifications

Inverter 3G3JX

3-phase 200-V Class

l	tem					3-phase	200-V class					
Model na	me (3G3JX-)		A2002	A2004	A2007	A2015	A2022	A2037	A2055	A2075		
Applicable motor	r kW	V	0.2	0.4	0.75	1.5	2.2	3.7	5.5	7.5		
capacity *1	HP	P	1/4	1/2	1	2	3	5	7.5	10		
Rated output cap	pacity 20	00V	0.4	0.9	1.3	2.4	3.4	5.5	8.3	11.0		
(kVA)	24	ΙΟV	0.5	1.0	1.6	2.9	4.1	6.6	9.9	13.3		
Rated input volta	ige		3-phase (3-w	3-phase (3-wire) 200 V -15% to 240 V +10%, 50/60 Hz ± 5%								
Built-in filter			Radio noise f	ilter								
Rated input current (A)			1.8	3.4	5.2	9.3	13.0	20.0	30.0	40.0		
Rated output vol	tage *2		3-phase: 200 to 240 V (according to the input voltage)									
Rated output cur	rent (A)		1.4	2.6	4.0	7.1	10.0	15.9	24.0	32.0		
Weight (kg)			0.8	0.9	1.1	2.2	2.4	2.4	4.2	4.2		
Cooling method			Self-cooling			Forced-air-co	cooling					
Braking ,	At short-time deceleration *3 At capacitor fe		Approx. 50%			,	Approx. 20% to 40%		Approx. 20%			
	DC injection braking		Injection brak	king frequency/ti	ime, braking for	ce variable, free	quency control a	available	<u>,</u>			

3-phase 400-V Class

Item					3-phase 400-V c	lass					
Model name (30	3JX-)	A4004	A4007	A4015	A4022	A4037	A4055	A4075			
Applicable motor	kW	0.4	0.75	1.5	2.2	3.7	5.5	7.5			
capacity *1	HP	1/2	1	2	3	5	7.5	10			
Rated output capacity	380V	0.9	1.6	2.5	3.6	5.6	8.5	10.5			
(kVA)	480V	1.2	2.0	3.1	4.5	7.1	10.8	13.3			
Rated input voltage		3-phase (3-wire) 380 V -15% to 480 V +10%, 50/60 Hz ± 5%									
Built-in filter		Radio noise filte	Radio noise filter								
Rated input current (A)		2.0	3.3	5.0	7.0	11.0	16.5	20.0			
Rated output voltage *2		3-phase: 380 to 480 V (according to the input voltage)									
Rated output current (A)	1.5	2.5	3.8	5.5	8.6	13.0	16.0			
Weight (kg)		1.5	2.3	2.4	2.4	2.4	4.2	4.2			
Cooling method		Self-cooling		Forced-air-coo	ling						
		Approx. 50%	Approx. 50%		Approx. 20% to 40%			Approx. 20%			
torque DC inje		Injection braking	g frequency/time,	braking force var	iable, frequency of	control available					

^{*1} The applicable motor is a 3-phase standard motor. For using any other type, be sure that the rated current does not exceed that of the Inverter.

^{*2} Output voltage decreases according to the level of the power supply voltage.

The braking torque at the time of capacitor feedback is an average deceleration torque at the shortest deceleration (when it stops from 50 Hz), not a continuous regeneration torque. Also, the average deceleration torque varies depending on the motor loss. The value is reduced in operation over 50 Hz. Note that no regenerative braking circuit is built into the Inverter. If you need a larger regenerative torque, use the optionally available regenerative braking unit and resistor.

The regenerative braking unit should be used only for short-time regeneration.

1/3-phase 200-V Class

Ite	m				1/3-phase 200-V Cla	ass			
Model name	e (3G3JX-)		AE002	AE004	AE007	AE015	AE022		
Applicable motor capac	situ *1	kW	0.2	0.4	0.75	1.5	2.2		
Applicable Illotor capac	Jily	HP	1/4	1/2	1	2	3		
Rated output capacity (LVA)	200V	0.4	0.9	1.3	2.4	3.4		
nated output capacity (kv	KVA)	240V	0.5	1.0	1.6	2.9	4.1		
Rated input voltage			1/3-phase 200 V -15	% to 240 V +10%, 50/6	0 Hz ± 5%				
Built-in filter			None						
Rated input current (A)		1-phase	3.1	5.8	9.0	16.0	22.5		
nateu iliput curreiit (A)		3-phase	1.8	3.4	5.2	9.3	13.0		
Rated output voltage *2			3-phase: 200 to 240 V (according to the input voltage)						
Rated output current (A	١)		1.4	2.6	4.0	7.1	10.0		
Weight (kg)			0.8	0.9	1.1	2.2	2.4		
Cooling method			Self-cooling			Forced-air-cooling			
Braking torque	At short-tindeceleration At capacito		Approx. 50%			Approx. 20% to 40%			
	DC injecti	on braking	Injection braking frequ	uency/time, braking for	ce variable, frequenc	uency control available			

The applicable motor is a 3-phase standard motor. For using any other type, be sure that the rated current does not exceed that of the Inverter.

Function Specifications

Inverter 3G3JX

	Item	Specifications					
Enclosure rating *	1	Semi-closed (IP20)					
	Control method	Phase-to-phase sinusoidal modulation PWM					
	Output frequency range *2	0.5 to 400 Hz					
	Frequency precision *3	Digital command: ±0.01% of the max. frequency Analog command: ±0.4% of the max. frequency (25°C ±10°C)					
	Frequency setting resolution	Digital setting: 0.1 Hz Analog setting: Max. frequency/1000					
Control	Voltage/Frequency characteristics	//f characteristics (constant/reduced torque)					
	Overload current rating	150% for 1 min					
	Acceleration/ Deceleration time	0.01 to 3000 s (line/curve selection), 2nd acceleration/deceleration setting available					
	Carrier frequency modification range	2 to 12 kHz					
	DC injection braking	Starts at a frequency lower than that in deceleration via the STOP command, at a value set lower than that during operation, or via an external input. (Level and time settable.)					
Protective functio	ns	Overcurrent, overvoltage, undervoltage, electronic thermal, temperature error, ground-fault overcurrent at power- on state, overload limit, incoming overvoltage, external trip, memory error, CPU error, USP trip, communication error, overvoltage protection during deceleration, momentary power interruption protection, emergency shutoff					
Input signal	Multi-function input	FW (forward), RV (reverse), CF1 to CF4 (multi-step speed), JG (jogging), DB (external DC injection braking), SET (2nd function), 2CH (2-step acceleration/deceleration), FRS (free run), EXT (external trip), USP (USP function), SFT (soft lock), AT (analog current input function selection), RS (reset), PTC (thermistor input), STA (3-wire startup), STP (3-wire stop), F/R (3-wire forward/reverse), PID (PID selection), PIDC (PID integral reset), UP (UP of UP/DWN function), DWN (DWN of UP/DWN function), UDC (data clear of UP/DWN function), OPE (forced OPE mode), ADD (frequency addition), F-TM (forced terminal block), RDY (operation ready), SP-SET (special setting), EMR (emergency shutoff)					
Outrot simpl	Multi-function output	RUN (signal during operation), FA1 (frequency arrival signal 1), FA2 (frequency arrival signal 2), OL (overload warning signal), OD (PID excess deviation signal), AL (alarm signal), DC (analog input disconnection detection signal), FBV (PID FB status output), NDc (network error), LOG (logical operation result), LOC (light load signal)					
Output signal	Frequency monitor	Analog output (0 to 10 V DC, 1 mA max.) Frequency/Current signals are selectable via the AM output terminal.					
	Relay output	The relay (SPDT contact) outputs signals corresponding to the multi-function output.					
Other functions		AVR function, V/f characteristic selection, upper/lower limit, 16-step speeds, starting frequency adjustment, jogging operation, carrier frequency adjustment, PID control, frequency jump, analog gain/bias adjustment, S-shape acceleration/deceleration, electronic thermal characteristics/level adjustment, retry function, simplified torque boost, trip monitor, soft lock function, frequency conversion display, USP function, 2nd control function, motor rotation speed UP/DOWN, overcurrent suppression function					
	Ambient temperature	-10°C to 50°C (Both the carrier frequency and output current need to be reduced at over 40°C.)					
	Ambient storage temperature	-20°C to 65°C (short-time temperature during transport)					
General specifications	Humidity	20% to 90% RH					
specifications	Vibration	5.9 m/s² (0.6G), 10 to 55 Hz (Complies with the test method specified in JIS C0040 (1999).)					
	Location	At a maximum altitude of 1,000 m; indoors (without corrosive gases or dust)					
	Applicable standard	Complies with UL, cUL, CE standards. (Insulation distance)					
Options	•	Noise filter, AC/DC reactors, regenerative braking unit and resistor, etc.					

Protection method complies with JEM 1030.

Output voltage decreases according to the level of the power supply voltage.

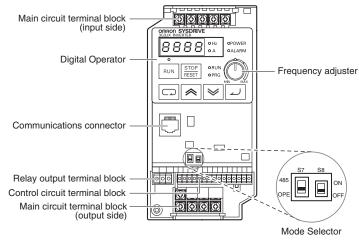
The braking torque at the time of capacitor feedback is an average deceleration torque at the shortest deceleration (when it stops from 50 Hz), not a continuous regeneration torque. Also, the average deceleration torque varies depending on the motor loss. The value is reduced in operation over 50 Hz. Note that no regenerative braking circuit is built into the Inverter. If you need a larger regenerative torque, use the optionally available regenerative braking unit and resistor.

The regenerative braking unit should be used only for short-time regeneration.

^{*2} To operate the motor at over 50/60 Hz, contact the motor manufacturer to find out the maximum allowable speed of recognitions and the stable control of the motor, the output frequency may exceed the maximum frequency set in A004 (A204) by 2 Hz max.

Components and Functions

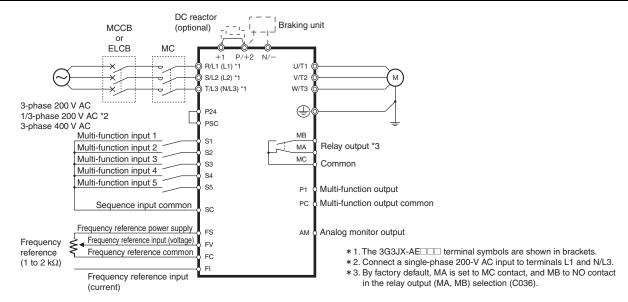
Inverter 3G3JX



Name	Function
Main circuit terminal block (input side)	Use this terminal block to connect the inverter to the main power supply.
Digital Operator	Used to set parameters, perform various monitoring, and start and stop the Inverter.
Frequency adjuster	Sets the frequency reference within a range between 0 Hz and the maximum frequency.
Communications connector	Use this connector to connect the Digital Operator or to connect the cable for RS-485 communication.
Relay output terminal block	Use this SPDT contact terminal block for relay outputs.
Control circuit terminal block	These terminal blocks are used to connect various digital/analog input and output signals for inverter control, etc.
Main circuit terminal block (output side)	Use this terminal block to connect an output to the motor.
Mode Selector	RS-485 Communication/Operator Selector (S7):Select the mode according to the option connected to the communications connector. Emergency shutoff selector (S8):Use this selector to enable the emergency shutoff input function

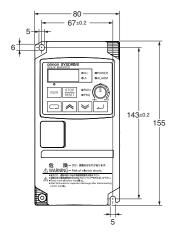
Note: This illustration shows the terminal block with the front cover removed.

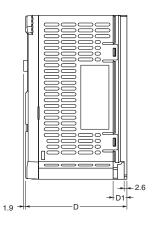
Connection Diagram



Dimensions (Unit: mm)

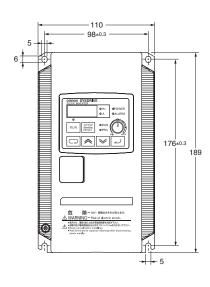
3G3JX-A2002 3G3JX-A2004 3G3JX-A2007 3G3JX-AE002 3G3JX-AE004

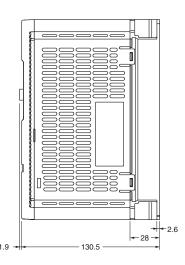




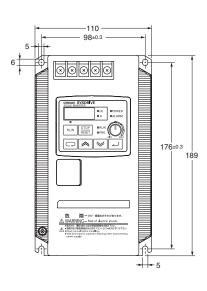
Rated voltage	Model 3G3JX	Dimensions (mm)		
voitage		D	D1	
	A2002	95.5	13	
3phase 200 V AC	A2004	109.5	27	
200 1 710	A2007	132.5	50	
1/3phase	AE002	95.5	13	
200 V AC	AE004	109.5	27	

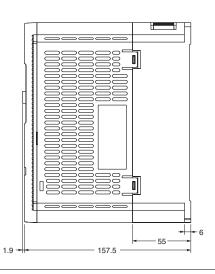
3G3JX-A4004 3G3JX-AE007



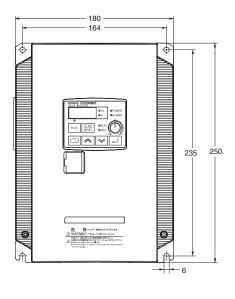


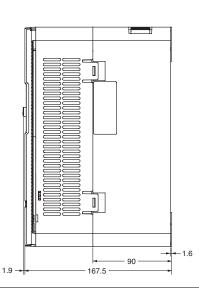
3G3JX-A2015 3G3JX-A2022 3G3JX-A2037 3G3JX-A4007 3G3JX-A4015 3G3JX-A4022 3G3JX-A4037 3G3JX-AE015 3G3JX-AE022





3G3JX-A2055 3G3JX-A2075 3G3JX-A4055 3G3JX-A4075





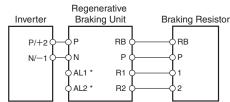
Options

Regenerative Braking Unit 3G3AX-RBU□□

Used with a Braking Resistor when regenerative energy is produced in the 3G3JX.



●Connection Example



The alarm output terminals for the Regenerative Braking Unit. Provide a circuit to turn off the primary power supply for the Inverter when the temperature relay of the built-in resistor or optional Braking Resistor is activated.

Note: When mounting an external Braking Resistor, remove the built-in resistor.

Specifications

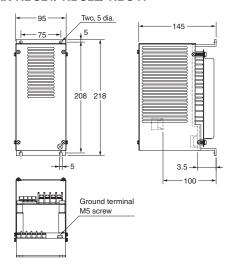
Built-in Resistance Type (3G3AX-RBU21/-RBU22/-RBU41)

С	lass	3-phase 2	200 V class	3-phase 400 V class				
Model na	me (3G3AX-)	RBU21	RBU22	RBU41 *1				
Connection resis	stance	17 Ω min.	17 Ω min.	34 Ω min.				
Operating voltag	e ON/OFF	ON: 362.5±5 V, OFF: 355±5 V (-5% or -10% setting available)		ON: 725±5 V, OFF: 710±5 V (-5% or -10% setting available)				
Operation indicate	tion	LED ON (Lit)						
Maximum number of units for parallel interlocking operation 2		5 units						
	Built-in resistance	120 W 180	120 W 20	120 W 180 × 2 main elements				
Built-in resistor	Allowable consecutive ON time	10s max.	0.5s max.	10s max.				
	Allowable operation cycle	Cycle 1/10 (10 s ON/90 s OFF)	Cycle 1/80 (0.5 s ON/40 s OFF)	Cycle 1/10 (10 s ON/90 s OFF)				
	Power consumption	Instantaneous: 0.73 kW Short-time rating: 120 W	Instantaneous: 6.6 kW Short-time rating: 120 W	Instantaneous: 1.46 kW Short-time rating: 240 W				
Protective functions	Built-in Resistor Overheat protection	Built-in relay specifications The temperature relay operates if the Built-in temperature fuse (recovery im Contact rating 250 VAC 200 mA (F) 12 VDC 500 mA (R) 42 VDC 200 mA (R) Minimum load 1mA	and recovers at approx. 170 ° possible) '3 R load) load)j					
	Ambient temperature	−10 to 50 °C						
Operating	Ambient storage temperature	-20 °C to 65 °C (short-time temperature	e during transport)					
environment	Humidity	20% to 90% (with no condensation)						
	Vibration	5.9 m/s ² (0.6 G) 10 to 55 Hz						
	Location	At a maximum altitude of 1,000 m; indo	ors (without corrosive gases or dust)					
Paint color		Munselle 5Y7/1 (cooling fan: aluminum	color)					

- To use the Regenerative Braking Unit for 1.5 kW or more 200 V class or the 2.2 kW or more 400 V class, be sure to remove the built-in resistor. Set the DIP switches.
- The built-in resistor incorporates a temperature fuse. If the alarm terminal is not connected, the fuse may blow out in order to prevent the resistor burning due to overheating. If the fuse blows out, the built-in resistor must be replaced.

●Dimensions (Unit: mm)

3G3AX-RBU21/-RBU22/-RBU41



Braking Resistor 3G3AX-RB□□□□□

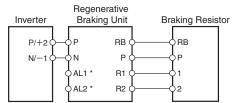
Consumes the regenerative motor energy with a resistor to reduce deceleration time.







●Connection Example



The alarm output terminals for the Regenerative Braking Unit. Provide a circuit to turn off the primary power supply for the Inverter when the temperature relay of the built-in resistor or optional Braking Resistor is activated.

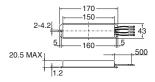
Note: When mounting an external Braking Resistor, remove the built-in resistor.

Specifications

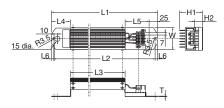
Model		Compact type (3G3AX-RBA□□□□)					Standard type (3G3AX-RBB□□□□)				Medium capacity type (3G3AX-RBC□□□□)		
		1201	1202	1203	1204	2001	2002	3001	4001	4001	6001	12001	
Resis-	Capacity	120W	120W	120W	120W	200W	200W	300W	400W	400W	600W	1200W	
tance	Resistance (Ω)	180	100	50	35	180	100	50	35	50	35	17	
Allowable	braking frequency (%)	5	2.5	1.5	1.0	10	7.5	7.5	7.5	10	10	10	
Allowable braking t	e continuous time (s)	20	12	5	3	30	30	30	20	10 10 10		10	
Weight (kg)	0.27	0.27	0.27	0.27	0.97	0.97	1.68	2.85	2.5 3.6 6.5			
Fault det	ult detection function Built-in thermal (contact capacity 240 VAC, 2 A max., minimum current 5 mA), Normally ON (NC contact) Ruilt-in termal (contact capacity 240 VAC, 2 A max., minimum current 5 mA), Normally ON (NC contact)			Normally Contact cap		C3A(Rload),							
	Ambient temperature	-10 to 50	°C							•			
General	Humidity	20% to 90	% (RH) with	no conden	sation								
specifi-	Vibration	5.9 m/s (0	.6 G) 10 to 5	55 Hz Comp	lies with JIS	C0911							
cation	Location	At a maxir	num altitude	e of 1,000 m	; indoors (wi	thout corros	ive gases or	r dust)					
	Cooling method	Self-coolir	ng										

●Dimensions (Unit: mm)

3G3AX-RBA



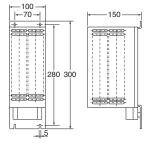
3G3AX-RBB



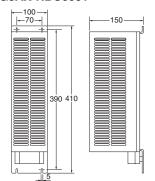
Model	Dimensions (mm)								
Wodei	L1	L2	L3	L4	L5	L6			
3G3AX-RBB2001	310	295	160	55	70	7.5			
3G3AX-RBB2002	310	295	160	55	70	7.5			
3G3AX-RBB3001	470	455	320	55	70	7.5			
3G3AX-RBB4001	435	422	300	50	60	6.5			

Model	[Dimensio	ons (mm)	Weight	Screw	
Wodei	H1	H2	w	Т	(kg)	size	
3G3AX-RBB2001	67	12	64	1.6	0.97		
3G3AX-RBB2002	67	12	64	1.6	0.97	M3.5	
3G3AX-RBB3001	67	12	64	1.6	1.68	IVI3.5	
3G3AX-RBB4001	94	15	76	2	2.85		

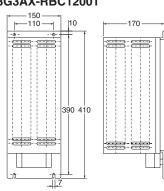
3G3AX-RBC4001



3G3AX-RBC6001

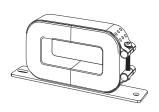


3G3AX-RBC12001



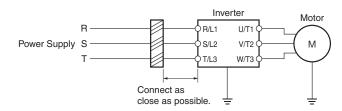
Radio Noise Filter 3G3AX-ZCL□

Connected to the inverter input/output cables to reduce noise coming into the inverter from the power supply line and noise flowing from the inverter into the power supply line.





●Connection Example



Note 1: Wind each of three phase wires in the same direction. 2: Can be used on both the input and output sides of the Inverter.

Specifications

3G3AX-ZCL1

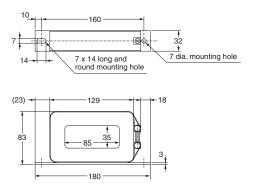
		200 V	class		400 V class				
Applicable	Inp	out	Out	tput	Inp	out	Output		
Inverter capacity (kW)	No. of fil- ters	No. of pene- tra- tions							
0.2	1	4	1	4	1	4	1	4	
0.4	1	4	1	4	1	4	1	4	
0.75	1	4	1	4	1	4	1	4	
1.5	1	4	1	4	1	4	1	4	
2.2	1	4	1	4	1	4	1	4	
3.7	1	4	1	4	1	4	1	4	
5.5	1	4	1	4	1	4	1	4	
7.5	1	4	1	4	1	4	1	4	

3G3AX-ZCL2

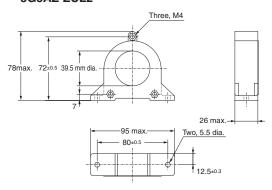
		200 V	class		400 V class				
Applicable	Input		Out	Output		out	Output		
Inverter capacity (kW)	No. of fil- ters	No. of pene- tra- tions							
0.2	1	4	1	4	1	4	1	4	
0.4	1	4	1	4	1	4	1	4	
0.75	1	4	1	4	1	4	1	4	
1.5	1	4	1	4	1	4	1	4	
2.2	1	4	1	4	1	4	1	4	
3.7	1	4	1	4	1	4	1	4	
5.5	N	N/A		N/A		4	1	4	
7.5	IN.					4	1	4	

●Dimensions (Unit: mm)

3G3AX-ZCL1

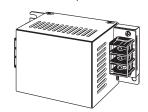


3G3AZ-ZCL2

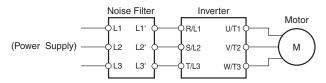


Input Noise Filter 3G3AX-NFI□□

Reduces noise coming into the inverter from the power supply line and noise flowing from the inverter into the power supply line. Connect as close to the Inverter as possible.



●Connection Example

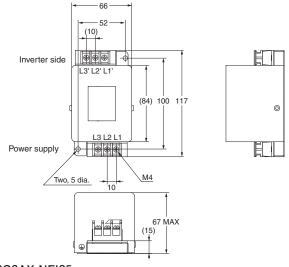


Specifications

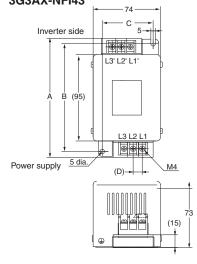
Power supply	Model	Applicable Inverter capacity (kW)	Rated input current In (A) at an ambient temperature of 50 °C	Power loss (W)	Leakage current (mA/ phase) at 60 Hz	Case enclosure rating	Terminal size	Wire dia.	Weight (kg)
	3G3AX-NFI21	0.2 to 0.75	3 × 6A	3	<1.5 (250V)	Plastic, IP00	M4	1.25mm ²	0.5
	3G3AX-NFI22	1.5	3 × 10A	4	<1.5 (250V)	Plastic, IP00	M4	2mm ²	0.6
3-phase 200 VAC	3G3AX-NFI23	2.2, 3.7	3 × 20A	6	<1.5 (250V)	Plastic, IP00	M4	2mm², 3.5mm²	0.7
	3G3AX-NFI24	5.5	3 × 30A	9	<1.5 (250V)	Plastic, IP00	M4	5.5mm ²	0.8
	3G3AX-NFI25	7.5	3 × 40A	12	<1.5 (250V)	Plastic, IP00	M5	8mm ²	1.4
	3G3AX-NFI41	0.4 to 2.2	3 × 7A	2	<7.5 (480V)	Plastic, IP00	M4	1.25mm ² , 2mm ²	0.7
3-phase 400 VAC	3G3AX-NFI42	3.7	3 × 10A	4	<7.5 (480V)	Plastic, IP00	M4	2mm ²	0.7
	3G3AX-NFI43	5.5, 7.5	3 × 20A	6	<7.5 (480V)	Plastic, IP00	M4	2mm², 3.5mm²	0.7

●Dimensions (Unit: mm)



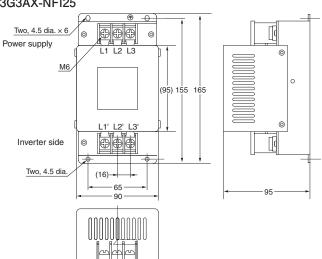


3G3AX-NFI23/3G3AX-NFI24 3G3AX-NFI41/3G3AX-NFI42 3G3AX-NFI43





3G3AX-NFI25



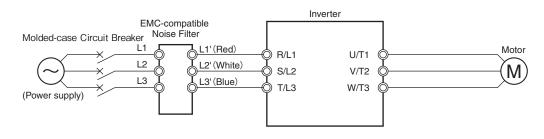
Model	Di	Dimensions (Unit: mm)								
wodei	Α	В	C	D						
3G3AX-NFI23	128	118	56	10						
3G3AX-NFI24	144	130	56	11						
3G3AX-NFI41	144	130	56	11						
3G3AX-NFI42	144	130	56	11						
3G3AX-NFI43	144	130	56	11						

EMC-compatible Noise Filter 3G3AX-EFI□□

Separately installed option used to comply with the EC's EMC Directives. Select a filter appropriate for the Inverter model.

●Connection Example



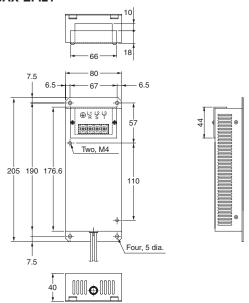


Specifications

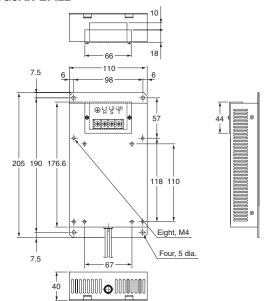
Power	Madal	Applicat	ole Inverter (kW)	capacity	Input current In	Leakage current	Case, Enclosure	Screw	Wire size	Weight
supply	Model	1-phase 200 V	3-phase 200 V	3-phase 400 V	(A)	(mA/phase at 60 Hz)	rating	size	wire size	(kg)
	3G3AX-EFIB1	0.2, 0.4			2 × 6A	15			1.3mm ²	0.43
1-phase 200 VAC	3G3AX-EFIB2	0.75			2 × 10A	15	Aluminum, IP20	M4	2.1mm ²	0.6
200 1710	3G3AX-EFIB3	1.5, 2.2			2 × 21A	15			3.3 to 5.3mm ²	0.88
	3G3AX-EFI21		0.2, 0.4		3 × 4A	15			1.3mm ²	0.56
	3G3AX-EFI22		0.75	0.4 to 1.5	3 × 5.2A	16		M4	1.3mm ²	0.72
3-phase 200 VAC	3G3AX-EFI23		1.5, 2.2	2.2, 3.7	3 × 14A	16	Aluminum, IP20	IVI 4	2.1mm ²	1.2
200 1710	3G3AX-EFI24		3.7		3 × 22A	16			3.3mm ²	1.3
	3G3AX-EFI25		5.5, 7.5	5.5, 7.5	3 × 40A	90		M5	3.3 to 8.4mm ²	2.4
	3G3AX-EFI41		0.4, 0.75	0.4 to 2.2	3 × 7A	150		144	1.25mm², 2mm²	0.7
	3G3AX-EFI42		1.5	3.7	3 × 10A	150		M4	2mm²	0.7
3-phase 200/400 VAC	3G3AX-EFI43		2.2, 3.7	5.5, 7.5	3 × 20A	170	Plastic, IP00		2mm², 3.5mm²	1.0
200, 100 VAO	3G3AX-EFI44		5.5		3 × 30A	170	1	M5	5.5mm ²	1.3
	3G3AX-EFI45		7.5		3 × 40A	170	1		8mm²	1.4

●Dimensions (Unit: mm)

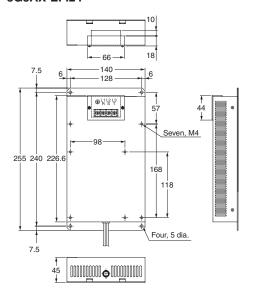
3G3AX-EFIB1 3G3AX-EFI21



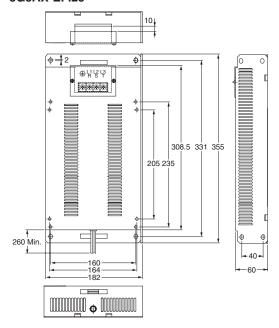
3G3AX-EFIB2 3G3AX-EFI22



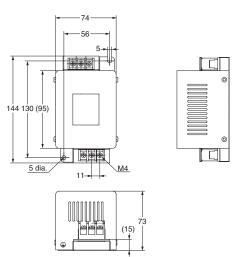
3G3AX-EFI24



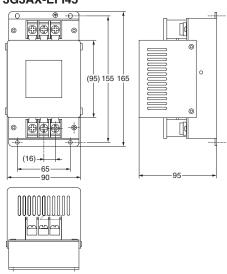
3G3AX-EFI25



3G3AX-EFI41 3G3AX-EFI42



3G3AX-EFI43/3G3AX-EFI44 3G3AX-EFI45

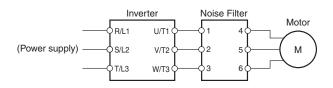


Output Noise Filter 3G3AX-NFO□□

Reduces noise generated by the Inverter. Connect as close to the Inverter as possible.



●Connection Example

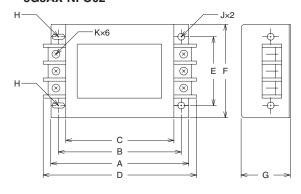


Specifications

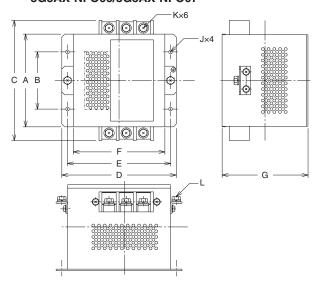
Power	Model	Rated current	Applicable	motor (kW)	External Dimensions	Weight
supply	Model	(A)	200 V class	400 V class	(H X W X D) (mm)	(kg)
	3G3AX-NFOO1	6	to 0.75	to 2.2	156 × 95 × 50	0.7
3-phase,3-wire	3G3AX-NFOO2	12	1.5, 2.2	3.7	176 × 110 × 70	0.9
Rated voltage 500 VAC	3G3AX-NFOO3	25	3.7, 5.5	5.5, 7.5	154 × 160 × 120	2.1
	3G3AX-NFOO4	50	7.5		210 × 200 × 150	3.7

●Dimensions (Unit: mm)

3G3AX-NFO01 3G3AX-NFO02



3G3AX-NFO03/3G3AX-NFO04/3G3AX-NFO05 3G3AX-NFO06/3G3AX-NFO07



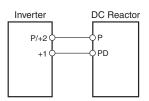
Model	Α	В	С	D	E	F	G	Н	J	K	L
3G3AX-NFO01	140	125	110	156	70	95	50	R: 2.25mm Length: 6mm	4.5 dia. mm	M4	
3G3AX-NFO02	160	145	130	176	80	110	70	R: 2.75mm Length: 7mm	5.5 dia. mm	M4	
3G3AX-NFO03	112	80	154	160	145	130	120		6.5 dia. mm	M4	
3G3AX-NFO04	162	100	210	200	180	160	150		6.5 dia. mm	M5	M5

DC Reactor 3G3AX-DL□□□□

Used to suppress harmonic current generated from the Inverter.

Suppresses harmonic current better than the AC Reactor and can be used with the AC Reactor.

●Connection Example



Specifications

Inverter Input		Figure	Applicable		D	imensi	ons (m	n) Bma	x: coil	dimen	sions		Weight	Standard
power supply	Model	No.	Inverter	W	D	Н	Α	В	X	Υ	С	К	(kg)	applicable wire
	3G3AX-DL2002		0.2	66	90	98		85	56	72	5.2 × 8	M4	8.0	1.25 mm ² min.
	3G3AX-DL2004		0.4	66	90	98		95	56	72	5.2 × 8	M4	1.0	1.25 mm ² min.
	3G3AX-DL2007	1	0.75	66	90	98		105	56	72	5.2 × 8	M4	1.3	2 mm² min.
3/1-phase	3G3AX-DL2015	'	1.5	66	90	98		115	56	72	5.2 × 8	M4	1.6	2 mm² min.
200 VAC	3G3AX-DL2022		2.2	86	100	116		105	71	80	6 × 9	M4	2.1	2 mm ² min.
	3G3AX-DL2037		3.7	86	100	118		120	71	80	6 × 9	M4	2.6	3.5 mm ² min.
	3G3AX-DL2055	2	5.5	111	100	210		110	95	80	7 × 11	M5	3.6	8 mm² min.
	3G3AX-DL2075	2	7.5	111	100	212		120	95	80	7 × 11	M6	3.9	14 mm ² min.
	3G3AX-DL4004		0.4	66	90	98		85	56	72	5.2 × 8	M4	0.8	1.25 mm ² min.
	3G3AX-DL4007		0.75	66	90	98		95	56	72	5.2 × 8	M4	1.1	1.25 mm ² min.
	3G3AX-DL4015		1.5	66	90	98		115	56	72	5.2 × 8	M4	1.6	2 mm ² min.
3-phase 400 VAC	3G3AX-DL4022	1	2.2	86	100	116		105	71	80	6 × 9	M4	2.1	2 mm² min.
100 1710	3G3AX-DL4037		3.7	86	100	116		120	71	80	6 × 9	M4	2.6	2 mm² min.
	3G3AX-DL4055		5.5	111	100	138		110	95	80	7 × 11	M4	3.6	3.5 mm ² min.
	3G3AX-DL4075		7.5	111	100	138		115	95	80	7 × 11	M4	3.9	3.5 mm ² min.

●Dimensions (Unit: mm)

W Ground terminal (M4)

MAX B

MAX H

Fig. 1

Fig. 2

Ground terminal (M5)

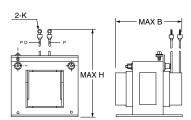
Y D

Y D

Y D

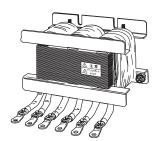
Y D

Y D

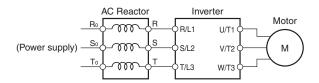


AC Reactor 3G3AX-AL□□□□

Connect the AC Reactor if the capacity of the power supply is much larger than that of the Inverter or the power factor is required to be improved.



●Connection Example

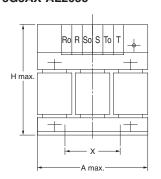


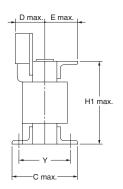
Specifications

		Applicable		Dimensions (mm)									
Power supply	Model	Inverter capacity (kw)	Α	С	D	E	Н	H1	Х	Υ	Weight (kg)		
	3G3AX-AL2025	0.2 to 1.5	130	82	60	40	150	92	50	67	2.8		
3-phase 200 VAC	3G3AX-AL2055	2.2, 3.7	140	98	60	40	150	92	50	75	4.0		
200 1710	3G3AX-AL2110	5.5, 7.5	160	103	70	55	170	106	60	80	5.0		
	3G3AX-AL4025	0.4 to 1.5	130	82	60	40	150	92	50	67	2.7		
3-phase 400 VAC	3G3AX-AL4055	2.2, 3.7	130	98	60	40	150	92	50	75	4.0		
100 1710	3G3AX-AL4110	5.5, 7.5	160	116	75	55	170	106	60	98	6.0		

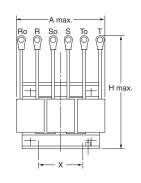
●Dimensions (Unit: mm)

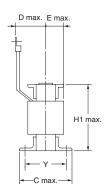
3G3AX-AL2025 3G3AX-AL2055



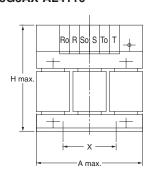


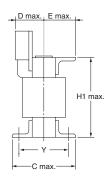
3G3AX-AL2110





3G3AX-AL4025/3G3AX-AL4055 3G3AX-AL4110





Digital Operator 3G3AX-OP01

Used to set parameters, perform various monitoring, and start and stop the Inverter.



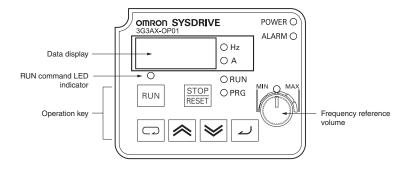
●Cables 3G3AX-OPCN□

Used to install the Digital Operator away from the Inverter.



3G3AX-OPCN1 (Cable length: 1 m) 3G3AX-OPCN3 (Cable length: 3 m)

●Dimensions (Unit: mm)



External Dimensions

Height (55 mm) X Width (70 mm) X Depth (10 mm)

Ordering Information

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Overview of Inverter Selection	22
Related Manuals	26
Other Products in the Inverter Series	26

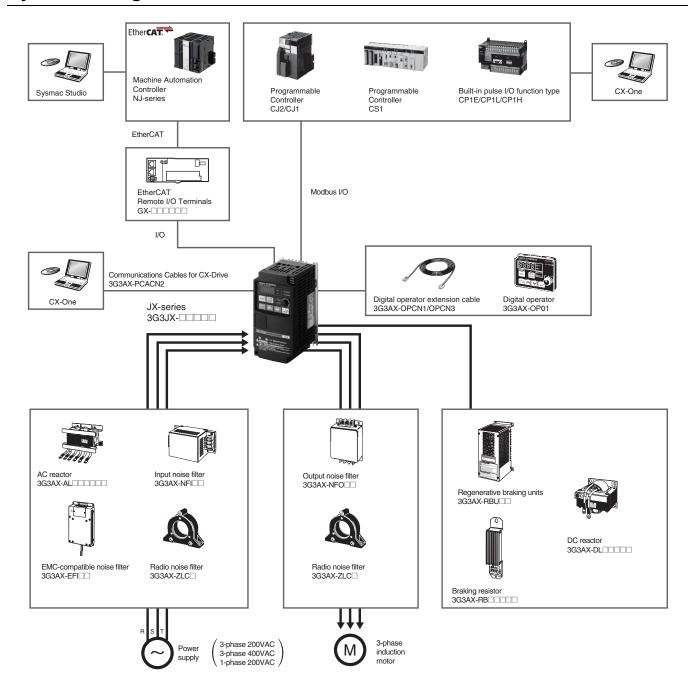
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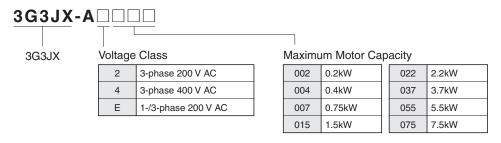
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System Configuration



Interpreting Model Numbers



Ordering Information

3G3JX Inverter Models

Rated voltage	Enclosure rating	Max. applicable motor capacity	Model
		0.2kW	3G3JX-A2002
		0.4kW	3G3JX-A2004
		0.75kW	3G3JX-A2007
0 = 1 = = = 000 \/ 40		1.5kW	3G3JX-A2015
3-phase 200 V AC		2.2kW	3G3JX-A2022
		3.7kW	3G3JX-A2037
		5.5kW	3G3JX-A2055
		7.5kW	3G3JX-A2075
		0.2kW	3G3JX-AE002
	IP20	0.4kW	3G3JX-AE004
1/3-phase 200 V AC	IF20	0.75kW	3G3JX-AE007
		1.5kW	3G3JX-AE015
		2.2kW	3G3JX-AE022
		0.4kW	3G3JX-A4004
		0.75kW	3G3JX-A4007
		1.5kW	3G3JX-A4015
3-phase 400 V AC		2.2kW	3G3JX-A4022
		3.7kW	3G3JX-A4037
		5.5kW	3G3JX-A4055
		7.5kW	3G3JX-A4075

Related Options

Name		Specifications	Model
		General purpose with Braking resistor	3G3AX-RBU21
Regenerative Braking Units	3-phase 200 VAC	High Regeneration purpose with Braking resistor	3G3AX-RBU22
	3-phase 400 VAC	General purpose with Braking resistor	3G3AX-RBU41
		Resistor 120 W, 180 Ω	3G3AX-RBA1201
	Compact type	Resistor 120 W, 100 Ω	3G3AX-RBA1202
	Compact type	Resistor 120 W, 50 Ω	3G3AX-RBA1203
		Resistor 120 W, 35 Ω	3G3AX-RBA1204
		Resistor 200 W, 180 Ω	3G3AX-RBB2001
Braking Resistor	Ctandard tune	Resistor 200 W, 100 Ω	3G3AX-RBB2002
	Standard type	Resistor 300 W, 50 Ω	3G3AX-RBB3001
		Resistor 400 W, 35 Ω	3G3AX-RBB4001
		Resistor 400 W, 50 Ω	3G3AX-RBC4001
	Medium capacity type	Resistor 600 W, 35 Ω	3G3AX-RBC6001
	1,7,8-2	Resistor 1200 W, 17 Ω	3G3AX-RBC12001

Regenerative Braking Unit and Braking Resistor Combination

- (1) Inverter specifications (choose voltage, capacity, and model)
 - The content noted in the table assumes the case of combining one Inverter and one motor of the same capacity.
- (2) Select the %ED.
 - Use the %ED that is equivalent to or lower than the value shown.
- (3) This shows the model and number of regenerative braking units and braking resistors.
- (4) This provides a summary of the connection configuration of the regenerative braking unit and braking resistor. Refer to the "Connection configuration"
- (5) The specified conditions contain restrictions. Make sure there are not any issues

	Inve	erter	Usage co	onditions	Regenerative braking	ng unit	Braking resistor		Con-	Restri	ctions
Voltage	Max. applicable motor capacity (kW)	Mode	%ED *1 (%)	Approximate braking torque (% '2)	Model	Num- ber of units	Model	Num- ber of units	nec- tion con- figu- ration	Allow- able con- tinuous braking time (s)	Min. con- nectable resis- tance (Ω)
	0.2	3G3JX-A2002	3.0%	220%	3G3AX-RBU21	1	Built-in Inverter		10	10	17
	0.2	3G3JX-AE002	10.0%	220%	3G3AA-NBUZT	1	Built-iii iiivertei		10	10	17
	0.4	3G3JX-A2004	3.0%	220%	3G3AX-RBU21	1	Built-in Inverter		10	10	17
	0.4	3G3JX-AE004	10.0%	220%	3G3AX-HB021	1	Duilt-iii iiivertei		10	10	17
	0.75	3G3JX-A2007	3.0%	120%	3G3AX-RBU21	1	Built-in Inverter		10	10	17
	0.75	3G3JX-AE007	10.0%	120%	3G3AA-NBUZT	1	Built-iii iiivertei		10	10	17
	1.5	3G3JX-A2015	2.5%	110%	3G3AX-RBU21 *3	1	3G3AX-RBA1202	1	11	12	17
200-V	1.5	3G3JX-AE015	10.0%	215%	3G3AX-HD0Z1	1	3G3AX-RBC4001	1	11	10	17
Class	2.2	3G3JX-A2022	3.0%	150%	3G3AX-RBU21 *3	1	3G3AX-RBB3001	1	11	30	17
	2.2	3G3JX-AE022	10.0%	150%	3G3AA-NBUZT	1	3G3AX-RBC4001	1	11	10	17
	3.7	3G3JX-A2037	3.0%	125%	3G3AX-RBU21 *3	1	3G3AX-RBB4001	1	11	20	17
	3.7	3G3JX-A2U37	10.0%	125%	3G3AA-NBUZT	1	3G3AX-RBC6001	1	11	10	17
	5.5	3G3JX-A2055	3.0%	120%	3G3AX-RBU21 *3	1	3G3AX-RBB3001	2	12	30	17
	3.3	3G33X-A2033	10.0%	120%	3G3AX-HB0Z1	1	3G3AX-RBC4001	2	12	10	17
	7.5	3G3JX-A2075	3.0%	125%	3G3AX-RBU21 *3	1	3G3AX-RBB4001	2	12	20	17
	7.5	3G33X-A2073	10.0%	130%	3G3AX-HB021	1	3G3AX-RBC12001	1	11	10	17
	0.4	3G3JX-A4004	3.0%	220%	3G3AX-RBU41 *3	1	Built-in Inverter		21	10	34
	0.4	3G33X-A4004	10.0%	220%	3G3AX-HB041	1	Duilt-iii iiiveitei		21	10	34
	0.75	3G3JX-A4007	3.0%	220%	3G3AX-RBU41 *3	1	Built-in Inverter		21	10	34
	0.75	3000X-A4007	10.0%	220%	JOSAX-NEO-1	1	Duilt-iii iiivertei		21	10	34
	1.5	3G3JX-A4015	3.0%	120%	3G3AX-RBU41 *3	1	Built-in Inverter		21	10	34
	1.5	3000X-A4013	10.0%	120%	JOSAX-NEO-1	1	Duilt-iii iiivertei		21	10	34
400-V	2.2	3G3JX-A4022	2.5%	150%	3G3AX-RBU41 *3	1	3G3AX-RBA1202	2	13	12	34
Class	2.2	3G33X-A4022	10.0%	220%	3G3AX-HB041	1	3G3AX-RBC4001	2	13	10	34
	3.7	3G3JX-A4037	3.0%	175%	3G3AX-RBU41 *3	1	3G3AX-RBB3001	2	13	30	34
	3.7	3000X-A4007	10.0%	175%	JOSAX-NEO-1	1	3G3AX-RBC4001	2	13	10	34
	5.5	3G3JX-A4055	3.0%	120%	3G3AX-RBU41 *3	1	3G3AX-RBB3001	2	13	30	34
	J.J	0000X-74000	10.0%	120%	OGOAN-HIDO41	1	3G3AX-RBC4001	2	13	10	34
	7.5	3G3JX-A4075	3.0%	125%	3G3AX-RBU41 *3	1	3G3AX-RBB4001	2	13	20	34
	7.5	CAGON NATURA	10.0%	125%	JOHN HEIGHT	1	3G3AX-RBC6001	2	13	10	34

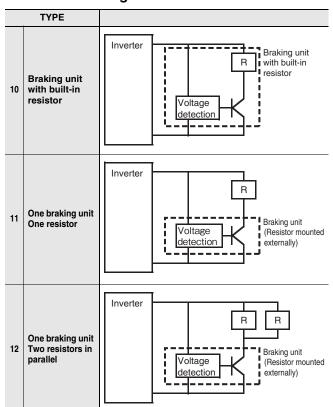
^{*1 %}ED shows the ratio that can be used for braking (deceleration time) among operating time of one task period.

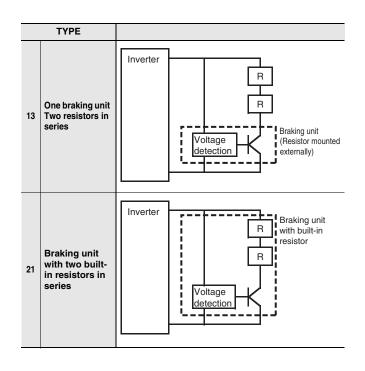
Note: When the torque more than the approximate braking torque is required or it is necessary to use more frequently than %ED, the selection including the load calculation instead of the combination list is required.

^{*2} Approximate breaking torque is shown in % of rating torque of the motor (100%).

^{*3} Please remove the built-in resistor.

Connection configuration





	Specific		
Name	Voltage class	Applicable capacity (kW)	Model
		0.2	
		0.4	
		0.75	20247 7012
	0 000 \/40	1.1	3G3AX-ZCL2
	3-phase 200 VAC	2.2	
		3	
		5.5	3G3AX-ZCL1
		7.5	(3G3AX-ZCL2)
		0.2	
D !' M ' F''		0.4	
Radio Noise Filter	1/3-phase 200 VAC	0.55	3G3AX-ZCL2
		1.1	
		2.2	
		0.75	
		1.5	
		2.2	
	3-phase 400 VAC	3	3G3AX-ZCL2 (3G3AX-ZCL1)
		4	(SGSAX-ZCLT)
		5.5	
		7.5	
		0.2 to 0.75	3G3AX-NFI21
		1.5	3G3AX-NFI22
	3-phase 200 VAC	2.2, 3.7	3G3AX-NFI23
		5.5	3G3AX-NFI24
Input Noise Filter		7.5	3G3AX-NFI25
		0.4 to 2.2	3G3AX-NFI41
	3-phase 400 VAC	3.7	3G3AX-NFI42
		5.5, 7.5	3G3AX-NFI43
		0.2, 0.4	3G3AX-EFIB1
	1-phase 200 VAC	0.75	3G3AX-EFIB2
		1.5, 2.2	3G3AX-EFIB3
		0.2, 0.4	3G3AX-EFI21
		0.75	3G3AX-EFI22
		1.5, 2.2	3G3AX-EFI23
		3.7	3G3AX-EFI24
		5.5, 7.5	3G3AX-EFI25
	3-phase 200 VAC	0.4, 0.75	3G3AX-EFI41
EMC-compatible Noise Filter		1.5	3G3AX-EFI42
		2.2, 3.7	3G3AX-EFI43
		5.5	3G3AX-EFI44
		7.5	3G3AX-EFI45
		0.4 to 1.5	3G3AX-EFI22
		2.2, 3.7	3G3AX-EFI23
		5.5, 7.5	3G3AX-EFI25
	3-phase 200/400 VAC	0.4 to 2.2	3G3AX-EFI41
		3.7	3G3AX-EFI42
		5.5, 7.5	3G3AX-EFI43

News	Specifications of Inverter			
Name	Voltage class	Applicable capacity (kW)	Model	
Output Noise Filter	3-phase 400 VAC	Applicable motor 200-V Class: to 0.75 400-V Class: to 2.2	3G3AX-NFO01	
		Applicable motor 200-V Class: 1.5, 2.2 400-V Class: 3.7	3G3AX-NFO02	
		Applicable motor 200-V Class: 3.7, 5.5 400-V Class: 5.5, 7.5	3G3AX-NFO03	
		Applicable motor 200-V Class: 7.5	3G3AX-NFO04	
		0.2	3G3AX-DL2002	
		0.4	3G3AX-DL2004	
		0.75	3G3AX-DL2007	
	4/0 = = = = 000 \/A0	1.5	3G3AX-DL2015	
	1/3-phase 200 VAC	2.2	3G3AX-DL2022	
		3.7	3G3AX-DL2037	
		5.5	3G3AX-DL2055	
DC Reactor		7.5	3G3AX-DL2075	
		0.4	3G3AX-DL4004	
		0.75	3G3AX-DL4007	
		1.5	3G3AX-DL4015	
	3-phase 400 VAC	2.2	3G3AX-DL4022	
		3.7	3G3AX-DL4037	
		5.5	3G3AX-DL4055	
		7.5	3G3AX-DL4075	
		0.2 to 1.5	3G3AX-AL2025	
	3-phase 200 VAC	2.2, 3.7	3G3AX-AL2055	
AC Reactor		5.5, 7.5	3G3AX-AL2110	
AC Reactor		0.4 to 1.5	3G3AX-AL4025	
	3-phase 400 VAC	2.2, 3.7	3G3AX-AL4055	
		5.5, 7.5	3G3AX-AL4110	

External Digital Operator

Name	Cable length	Model	
Digital Operator		3G3AX-OP01	
Connection cable	1m	3G3AX-OPCN1	
Connection cable	3m	3G3AX-OPCN3	

Software

Name	Specifications	Number of licenses	Media	Model
FA Integrated Tool Package CX-One Ver. 4.□	The CX-One is a comprehensive software package that integrates Support Software for OMRON PLCs and components. CX-One runs on following OS. OS: Windows XP (Service Pack 3 or higher), Vista or 7 Note: Note: Except for Windows XP 64-bit version. CX-One Version.4.□ includes CX-Drive Ver.2.□. For details, refer to the CX-One catalog (Cat. No.R134)	1 license *1	DVD *2	CXONE-AL01D-V4

^{*1} Multi licenses are available for the CX-One (3, 10, 30, or 50 licenses).
*2 The CX-One is also available on CD (CXONE-AL□□C-V4).

Communications Cable

Name	Specifications	Model
Communications cable for CX-Drive	USB Cable for JX and RX series (2m)	3G3AX-PCACN2

Overview of Inverter Selection

For detail of Inverter selection, refer to the JX series User's Manual. (Man.No.1558).

Motor Capacity Selection

Before selecting an invertor, first the motor should be chosen.In selecting the motor, first calculate the load inertia for the applications, and then calculate the required capacity and torque.

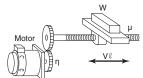
Make a simple selection (use Formulas for the required output power)

This method of calculation helps select a motor by calculating the output (W) required by the motor to maintain its regular rotations. It does not include calculation of the effect of acceleration/deceleration. Therefore, make allowance for the calculated value to select a motor. This calculation method can be applied to applications that operate constantly such as fans, conveyers, agitators etc.

This calculation method must not be applied to the following applications:

- •Those requiring instant start-up.
- •Those that frequently repeat operation and stop.
- •Those that have a large inertia at the power transfer part.
- •Those that have an inefficient power transfer part.

●For Straight-Line Operation: Normal Power PO [kW]



$$P_0 = \frac{\mu \cdot W \cdot V\ell}{6120 \cdot n}$$

u: Friction Coefficient

W: Mass of Straight-Line travelling part [kg] Vℓ: Speed of Straight-Line Travelling part [m/min] η: Decelerator (Transfer part) Efficiency

●For Rotating Operation: Normal Power PO [kW]



$$P_{o} [kW] = \frac{2\pi \cdot T\ell \cdot N\ell}{60 \cdot \eta} \times 10^{-3}$$

Tℓ: Load Torque (Load Shaft) [N·m] N €: Load Shaft Rotation Speed [r/min] η: Transfer part (η≤1)

Detailed Selection Method (R.M.S Algorithm)

This method helps to select a motor by calculating the effective torque and maximum torque required to achieve a certain pattern of operation for the application. It selects a motor that is optimal for a particular operation pattern.

Calculate the inertia with a Motor Shaft **Conversion Value**

Calculate inertias of all the components with the formula for inertia calculation shown below to convert them to a motor conversion value.



$$J_W = J_1 + J_2 = \left(\frac{M_1 \cdot D^2}{8} + \frac{M_2 \cdot D^2}{4}\right) \times 10^{-6} (kg \cdot m^2)$$

- J, : Cylinder Inertia (kg·m²)
- M.: Mass of Cylinder (kg)
- J_a: Inertia from Object (kg·m²)
- Ma: Mass of Object (kg)

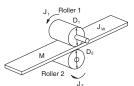
$$J_w = J_1 + J_2 + J_3 + J_4 = \left(\frac{M_1 \cdot D_1^2}{8} + \frac{M_2 \cdot D_2^2}{8} \cdot \frac{D_1^2}{D_2^2} + \frac{M_3 \cdot D_1^2}{4} + \frac{M_4 \cdot D_1^2}{4}\right) \times 10^{-6} (kg \cdot m^2)$$



- Jw: Inertia (kg·m²)
- J₁: Cylinder 1 Inertia (kg·m²)
- J₂: Inertia from Cylinder 2 (kg·m²)
 - M.: Mass of Cylinder 1 (kg)
- J₂: Inertia from Object (kg·m²)
- Mass of Cylinder 2 (kg) J₄: Inertia from Belt (kg·m²)
 - Mass of Object (kg)
 - M.: Mass of Belt (kg)

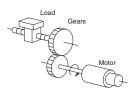
D.: Cylinder 1 Diameter (mm)

Da: Cylinder 2 Diameter (mm)



$$J_w = J_1 + \left(\frac{D_1}{D_2}\right)^2 J_2 + \frac{M \cdot D_1^2}{4} \times 10^{-6} (kg \cdot m^2)$$

- J₁: Roller 1 Inertia (kg·m²)
- J₂: Roller 2 Inertia (kg·m²)
- D.: Roller 1 Diameter (mm)
- D₂: Roller 2 Diameter (mm)
- M : Work Equivalent Mass (kg)



$$J_1 = J_1 + G^2(J_2 + J_w) (kg \cdot m^2)$$

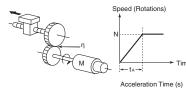
- J.: Load Inertia of Motor Shaft Conversion (kg·m²)
- J...: Load Inertia (kg·m²)
- J.: Gear Inertia on Motor Side (kg·m²)
- J₂: Gear Inertia on Load Side (kg·m²)
- Z, : Number of Gear Teeth on Motor Side
- Z : Number of Gear Teeth on Load Side

Gear Ratio G = Z₁/Z₂

Calculate Motor Shaft Conversion Torque and **Effective Torque**

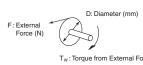
Calculate the acceleration torque from the load torque calculated from both the motor shaft conversion value and the motor rotor inertia. Then Combine this acceleration torque and the Load torque calculated from the friction force and the external force that are applied to the load. Now you get the required torque to operate a motor.

Acceleration Torque



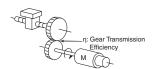
- T_A: Acceleration/Deceleration Torque (N·m)
- J_L: Motor Shaft Conversion Load Inertia (kg·m2)
- J_M : Inertial of Motor Itself (kg⋅m²)
- η : Gear Transmission Efficiency
- N: Motor Rotation Speed (r/min)

Motor Shaft Conversion Load Torque (External Force/Friction)



 $T_W = \ F \cdot \frac{D}{2} \times 10^{-3} \, (\text{N} \cdot \text{m})$

(Friction is generally, μ: Friction Coefficient $F = \mu W$ W: Mass of Moving Part)



$$T_L = T_W \cdot \frac{G}{\eta} (N \cdot m)$$

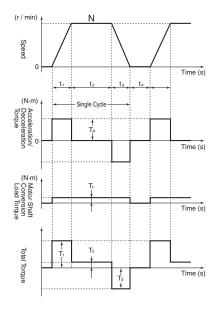
- T_1 : Motor Shaft Conversion Load Torque (N·m)
- Tw: Load Torque (N-m)
- Z,: Number of Gear Teeth on Motor Side
- Z₂: Number of Gear Teeth on Load Side
- Gear (Deceleration) Ratio G = Z₁/Z₂

Calculation of Total Torque and Effective Torque

Effective Torque: TRMS (N·m)

$$= \ \sqrt{ \frac{ \ \Sigma \left(T_{i} \right)^{2} \cdot t_{\ i} }{ \ \Sigma t_{\ i} } } \ = \ \sqrt{ \frac{ T_{1}^{2} \cdot t_{1} + T_{2}^{2} \cdot t_{2} + T_{3}^{2} \cdot t_{3} + T_{4}^{2} \cdot t_{4} }{ t_{1} + t_{2} + t_{3} + t_{4} } }$$

Maximum Torque: $T_{MAX} = T_1 = T_A + T_L$



Note: Please make use of the Servo Motor selection software, which can calculate the motor shaft conversion inertia and effective/maximum torque, as above.

Motor Selection

Use the formula below to calculate the motor capacity from the effective torque and the maximum torque that were obtained above. Select the larger of the two generated values as the motor capacity. Select a motor the capacity of which is larger than the calculated value and makes allowance for an error.

• Motor Capacity corresponding to Effective Torque

Motor Capacity [kW] = 1.048·N·T_{RMS}·10⁻⁴ N: Maximum Rotations (r/min)

Motor Capacity capable of Providing Maximum Torque

Motor Capacity [kW] = $1.048 \cdot N \cdot T_{MAX} \cdot 10^{-4} / 1.5$ N: Maximum Rotations (r/min)

Inverter Capacity Selection

Select an inverter that can be used for the selected motor in the process of "Motor Selection".

Generally, select an inverter which fits the maximum applicable motor capacity of the selected motor.

After selecting an inverter, check if it meets with all of the following conditions. If it does not, select an inverter that has a one class larger capacity and check the feasibility again.

Motor Rated Current \leq Inverter Rated Output Current Maximum Time of Continuous Torque Output Time in an Application \leq 1 minute

Note: 1. Where the inverter overload capacity is "120% of Rated Output Current for 1 minute", check it for 0.8 minute.

2. Where a 0 Hz sensor-less vector control is being used, or where torque must be maintained for 0 (r/min) rotation speed and where 150% of the rated torque is frequently required, use an invertor which is one rank larger than the one selected by the above method.

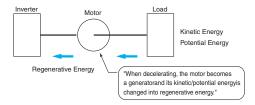
Outline of Braking Resistor Selection Importance of Braking Resistor

If the regenerative energy generated in deceleration or descent in an application is too great, the main circuit of an inverter may have an increased voltage and it may be damaged.

Because the inverter usually contains the overvoltage LAD stop function, it is not actually damaged. However, the motor stops detecting an error, making a stable and continuous operation disabled. Therefore, you must discharge the regenerative energy outside of the inverter.

• What is Regenerative Energy?

A load connected to a motor has kinetic energy when rotating, and potential energy when it is located in a high position. When the motor decelerates, or when the load descends, the energy is returned to an inverter. It is known as regeneration, and the energy generated by the phenomenon is known as regenerative energy.



Preventing Breaking Resistence

The following are methods to prevent the connection of braking resistance.

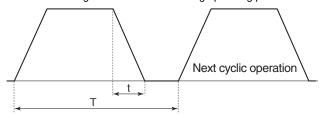
These methods will make the deceleration time increase, so check if it will not cause problems.

- Enable the deceleration stall prevention (enabled in factory settings) (It will automatically increase deceleration time not to cause an overvoltage to stop the motor).
- Set a longer deceleration time. (Cause the regenerative energy to decrease per unit of time.)
- Disable Free-Run. (Prevent the regenerative energy from returning to an inverter.)

Make a Simple Selection for Braking Resistors

It can be a simple selecting method by using the ratio of time in which regenerative energy is produced in a normal operating pattern.

Calculate the usage ratio from the following operating pattern.



Usage Rate = $t/T \times 100$ (% ED)

- t : Deceleration Time (Regenerative Time)
- T: Single Cycle Operation Time

%ED is the unit used for a usage rate.

The usage rate is used as the ratio of deceleration time (regenerative operation time) to simplify the selection of the braking options.

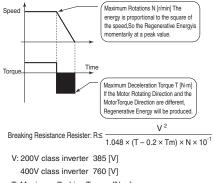
For Models without a Built-in Braking Circuit (3G3JX)

Select the regenerative braking unit and the braking resistor. Refer to the regenerative braking unit and braking resistor lists described in the User's manual and catalog, and connect them according to your Inverter.

Make a Simple Selection of Braking Resistor

When the usage ratio for the braking resistor selected on the previous page exceeds 10% ED, or when an extremely large braking torque is required, use the method below to calculate a regenerative energy and make your selection.

Calculation of Required Braking Resistor



T: Maximum Braking Torque [N·m]

Tm: Motor Rated Torque [N·m]

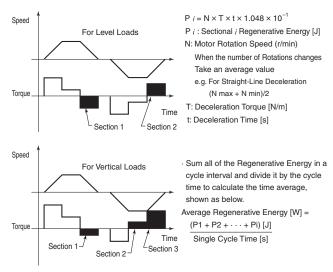
N: Maximum Rotation Speed [r/min]

Note: Calculate a braking torque using the above "Motor Capacity Selection"

● Calculation of Average Regenerative Energy

Regenerative Energy is produced when the motor rotation direction and the torque direction are opposite.

Use the following formula to calculate a regenerative energy per cycle interval.



- **Note: 1.** Forward rotation direction is forward for the speed, and the torque in the forward rotation direction is forward for the torque.
 - Calculate a braking torque using the above "Motor Capacity Selection".

Braking Resistor Selection

Select a Braking Resistor from the required braking resistance and average regenerative energy on the left.

- Required Braking Resistence ≥ Resistence of Braking Resistor ≥ Minimum Connection Resistence of Invertor or Regenerative Braking Unit
- Average Regenerative Energy ≤ Permissible Power for Braking Resister
- Note: 1. If a resistance that has a less then the minimum connectable value is connected on an inverter or regenerative braking resistor unit, the internal breaking transistor can be damaged. When the required braking resistance is less than the minimum connectable resistance, change the inverter or regenerative energy braking to the one having a larger capacity and a minimum connection resistance less than the required braking resistance.
 - 2. Two or more regenerative braking units can be operated in parallel. Refer to the following formula to know the braking resistance value in such a case. Braking Resistence(Ω) = (Required Braking Resistance as calculated above) × (No. of Units in use)
 - 3. Do not use the above formula to select a generative braking resistance value. 150W does not reflect a permissible power capacity, but the maximum rated power per unit of resistance. The actual permissible power varies according to a resistance.

Related Manuals

Man.No.	Model	Manual
1558	3G3JX	JX series Compact Simplified Inverters User's Manual
W463	CXONE-AL C/D-V	CX-One FA Integrated Tool Package Setup Manual
W453	CXONE-AL□□C/D-V□ WS02-DRVC01	CX-Drive OPERATION MANUAL

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Capacity

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OMRON Corporation Industrial Automation Company

Tokyo, JAPAN

Contact: www.ia.omron.com

Regional Headquarters OMRON EUROPE B.V.

Wegalaan 67-69-2132 JD Hoofddorp The Netherlands Tel: (31)2356-81-300/Fax: (31)2356-81-388

OMRON ASIA PACIFIC PTE. LTD.
No. 438A Alexandra Road # 05-05/08 (Lobby 2),
Alexandra Technopark,
Singapore 119967 Tel: (65) 6835-3011/Fax: (65) 6835-2711

OMRON ELECTRONICS LLC

One Commerce Drive Schaumburg, IL 60173-5302 U.S.A. Tel: (1) 847-843-7900/Fax: (1) 847-843-7787

OMRON (CHINA) CO., LTD. Room 2211, Bank of China Tower, 200 Yin Cheng Zhong Road, PuDong New Area, Shanghai, 200120, China Tel: (86) 21-5037-2222/Fax: (86) 21-5037-2200

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